Declass review by NGA/DoD

Approved For Release 2005/06/23 : CIA-RDP78B05171A000400030049-7

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3,3 Specifications

MLT-1540-4 Light Tables which have been modified for a mensuration capability will meet the following specifications with any specified optical instruments mounted. The following Spec Nos. 1-9 and 12-14 are to be met with the optics carriage in the motorized drive/locked mode.

1. X-Y minimum starting and operating speed

0.005 in ./sec. ± 10%

2. X-Y naximum speed

> .250 in ./sec.

3. Time to attain set speed

0.5 to 1.0 sec. or less

4. Time from release of control to stop

0.1 sec. or less

- 5. Speed of X travel of bridge equal to speed of Y travel of bridge within 10%.
- 6. For any setting of the speed control, the time for an increment equivalent to 0.2 seconds of motion at that nominal speed setting shall not vary from he time for the previous incremen by more than  $\pm$  5%.
- 7. Control of carriage speed by speed control shall be approximately logrithmic with slow response at low speed.
- 8. X-Y : peed control shall have no dead band, i.e., minimum speed shall occur at minimum setting of control.
- 9. X-Y direction switch shall be lever actuated.
- 10. Movement of microscope carriage and mount when electrically locked in X and Y within the following limitation:

Pressure Applied

Allovable Movement

2 lbs.

.010"

4 lbs.

.020"

Measurement method is as follows:

- A specified force applied in plus direction
- Deflection gage zeroed with force applied
- Specified force applied in minus direction
- Deflection read with minus force applied
- 11. Force for manual movement of carriage in X and Y directions will be as low as possible commensurate with the above requirements not exceeding 4 pounds.

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- 12. At any selected setting of the speed control the variation from that speed shall not exceed  $\pm$  20% of that speed.
- 13. It shall be possible to electrically drive the carriage in X and/or Y when the X and Y locks are engaged. Stopping and starting in both X and Y shall not involve engagement or disengagement of clutches.
- 14. It is required that an operator be able to electrically "nudge" the carriage to allow final pointing of an object. Idemonstrated equipment in July 1971 capable of operator induced electrical movement of approximately .0005". Such movement assumes maximum quick off-on response by the operator. It is the intent of both parties that the completed table will function in this regard equal to the above demonstration.

## 4.0 ALTERNATE THREE - Y BRIDGE DRIVE DISCONNECT

## 4.1 Approach

Present MLT-1540 specifications require a force of less than 4 lbs. for manual movement of the microscope bridge and carriage. For manual scanning it is desired to have a force of less than 2 lbs. Present MLT-1540 Light Tables require a force of less than 2 lbs. for movement of the microscope in the X direction, however forces approaching 4 lbs. are required for Y. By disconnecting the bridge from the Y drive chain, forces of less than 2 lbs. for bridge movement can be achieved. This proposed modification will provide for manually disconnecting the Y bridge drive chains. In addition, interlock switches will be provided so that the tilt motor may not be operated when the bridge is disconnected from the chains. It should be noted that there is no automatic fail safe feature and if the bridge drive is disconnected when the bridge is in a tilted position the bridge may fall. Suitable caution signs will be provided.

## 4.2 Modification Description

The Y drive chain disconnect mechanism will consist of a lever actuated over center cam with a spring loaded return. The cam will actuate a pair of parallel rods

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conne	cted together at the ends by tie bars. When in the locked position the end piece
of the	rods is forced against the chain by the eccentric cam located at the opposite end
free m	rods. In the unlocked position the end piece is moved away from the chain allowing
the ve	rtical down position (unliably to a manually operated by a handle that rotates from
, 0	rtical down position (unlock) to a position parallal with the MLT table top (locked).
cam ho	A limit switch will operate in conjunction with the over center cam. When the
motor	is energized. In the unlock position the filt motor is disabled. This assures the
tilt mo	tor will not operate when the Y drive chain is unlocked.
4.3	Specifications
	•
	Bridge may be freed in Y by lever actuat ≥d disconnect
	• Manual force required to move Y bridge when freed 1 1/2 lbs. ± 1/2 lb.
	• Manual force required to move X bridge 1 1/2 lbs. ± 1/2 lb.
	. Interlock provided to disable tilt motor when drive is disconnected.
5.0	STATEMENT OF WORK
5.1	Alternate One
	In providing the modification proposed in Section 2.0 of this proposal
	will:
	1. Provide printed circuit boards without relays which will contain the
	necessary circuitry for performance of the MLT-1540 in accordance
	with specifications listed in Paragraph 2.3.  2. Install and checkout each of the modifications.
	3. Revise present ATP to include new features,
	4. Begin delivery within 12 weeks after receipt of order.
.2	Alternate Two
•-	
-	In providing the modifications listed in Section 3.0 of this proposal will:

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	, i	1. Provide a modification kit to modify the MLT 1540-4 for pe	orformánao in
7		accordance with the specifications listed in paragraph 3.3.	errormance in
		2. Install and check out each modification. (20 field; 26 fact	ory)
	1	3. Revise present ATP to include new features.	$(x,y) = \frac{t}{t} \left( \frac{1}{t} \left( \frac{t}{t} \right) + \frac{t}{t} \right) \left( \frac{t}{t} \right) = \frac{t}{t} \left( \frac{t}{t} \right)$
		4. Begin delivery within 12 weeks after receipt of order.	
	5.3	Alternate Three	
т.		In providing the modification listed in Section 4.0 of this propowill:	sal ST
•		<ol> <li>Provide a modification to modify the MLT-1540 in accordant Section 4.0.</li> </ol>	nce with
ř.		, 2. Install and check out each modification. (20 field; 26 factors)	ory)
		3. Revise present ATP to include new features.	
	•	· 4. Begin delivery within 12 weeks after receipt of order.	Tini mi Aliini
	6.0	TERMS AND CONDITIONS	
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Т	under	The terms and conditions of this proposal shall be as mutually ag	reed_upon
	7 <b>.</b> 0	PRICING	<del></del>
	7.0	FRICING	
	describe Terms ar	Based on a firm fixed price supply type contract, prices for the nd in this proposal in accordance with the Statement of Work, Section Conditions, Section 6.0, are:	on 5.0, and
		Alternate 1	
		Quantity 25	ST
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		Y drive point modification  Drive electronics modifications	
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